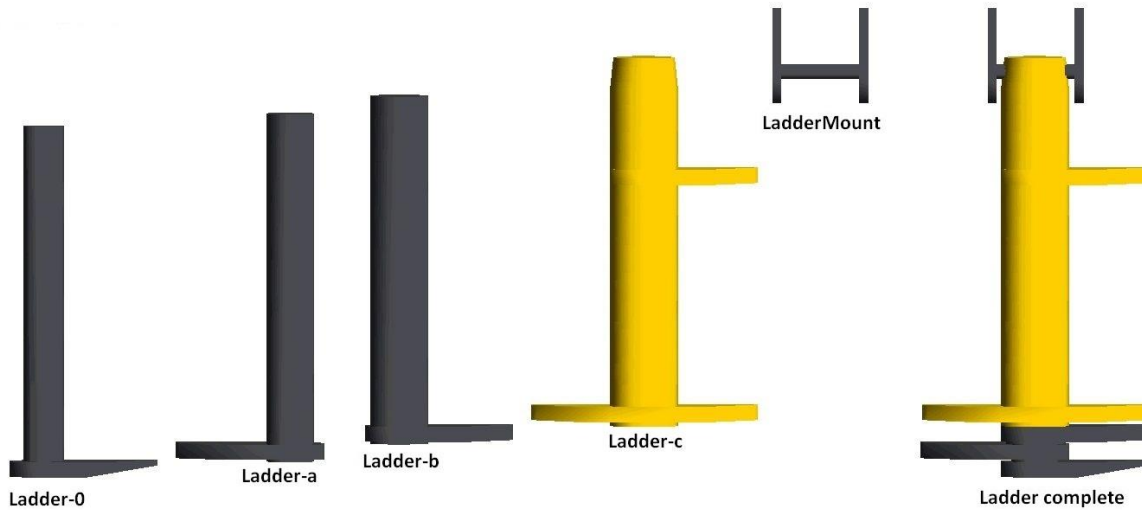


Moving cockpit and pilot ladder (Thunderbolt A10)



```

<[string8][object][rigidbody]
  <[string8][Name][Ladder]>
  <[float64][Mass][0.01]>
  <[tmvector3d][InertiaLength][0.069100 0.027600 0.127300]>
  <[tmvector3d][R0][1.021900 0.113100 0.080000]>
  <[tmmatrix3d][B0][1.0 0.0 0.0 0.0 1.0 0.0 0.0 0.0 1.0]>
>
<[string8][object][jointlinear]
  <[string8][Name][LadderJoint1]>
  <[tmvector3d][R0][1.022300 0.099300 0.137700]>
  <[float64][Kfx][1000.0]>
  <[float64][Kfy][1000.0]>
  <[float64][Kfz][1000.0]>
  <[float64][Dfx][0.5]>
  <[float64][Dfy][0.5]>
  <[float64][Dfz][0.5]>
  <[float64][Ktx][100.0]>
  <[float64][Kty][100.0]>
  <[float64][Ktz][100.0]>
  <[float64][Dtx][0.002]>
  <[float64][Dty][0.002]>
  <[float64][Dtz][0.002]>
  <[string8][Body0][Fuselage]>
  <[string8][Body1][Ladder]>
  <[float64][ForceMax][600.0]>
  <[float64][TorqueMax][600.0]>
  <[string8][Rotation0Control][ServoLadderRotation.Output]>
  <[tmvector3d][Rotation0Axis][0.999048 0.000000 0.043619]>
  <[float64][Rotation0Angle][-0.3]>
>

```

```
<[string8][object][servolinear]
  <[string8][Name][ServoCockpitSequence]>
  <[string8][Input][CanopyInput.Output]>
  <[float64][OutputSpeed][0.2]>
  <[float64][Position][0.0]>
  <[float64array][InputPosition][ 0.0 1.0 ]>
  <[float64array][OutputPosition][ 0.0 1.0 ]>
>
<[string8][object][servolinear]
  <[string8][Name][ServoCockpit]>
  <[string8][Input][ServoCockpitSequence.Output]>
  <[float64][OutputSpeed][10.0]>
  <[float64][Position][0.0]>
  <[float64array][InputPosition][ 0.0 0.25 ]>
  <[float64array][OutputPosition][ 0.0 1.0 ]>
>
<[string8][object][servolinear]
  <[string8][Name][ServoLadderRotation]>
  <[string8][Input][ServoCockpitSequence.Output]>
  <[float64][OutputSpeed][10.0]>
  <[float64][Position][0.0]>
  <[float64array][InputPosition][ 0.0 0.4 0.6 ]>
  <[float64array][OutputPosition][ 0.0 0.0 1.0 ]>
>
<[string8][object][servolinear]
  <[string8][Name][ServoLadderTranslation]>
  <[string8][Input][ServoCockpitSequence.Output]>
  <[float64][OutputSpeed][10.0]>
  <[float64][Position][0.0]>
  <[float64array][InputPosition][ 0.0 0.8 1.0 ]>
  <[float64array][OutputPosition][ 0.0 0.0 1.0 ]>
>
.
.
.
<[string8][object][hingedbodygraphics]
  <[string8][Name][Cockpit]>
  <[string8][GeometryList][ Canopy CanopyGlass ]>
  <[uint32][PositionID][Fuselage.R]>
  <[uint32][OrientationID][Fuselage.Q]>
  <[uint32][AngleID][ServoCockpit.Output]>
  <[tmvector3f][Axis][0 1 0]>
  <[tmvector3f][Pivot][0.602300 0.000000 0.338200]>
  <[float64][AngleMax][0.5]>
>
<[string8][object][hingedbodygraphics]
  <[string8][Name][LadderDoor]>
  <[string8][GeometryList][ LadderDoor-i LadderDoor-i-1 LadderDoor-o ]>
  <[uint32][PositionID][Fuselage.R]>
  <[uint32][OrientationID][Fuselage.Q]>
  <[tmvector3f][Axis][ 0.0000 0.0000 1.0000 ]>
  <[tmvector3f][Pivot][1.064400 0.128000 0.076100 ]>
  <[uint32][AngleID][ServoCockpit.Output]>
  <[float64][AngleMax][3]>
>
```

```
<[string8][object][graphics_input]
  <[string8][Name][LadderRotation]>
  <[string8][InputID][ServoCockpit.Output]>
  <[float64][Scaling][-0.4]>
>
<[string8][object][graphics_rotation]
  <[string8][Name][Step1Rotation]>
  <[tmvector3f][Axis][ 0.999048 0.000000 0.043619 ]>
  <[tmvector3f][Pivot][1.022300 0.099300 0.137700 ]>
  <[float64][InputAngle][LadderRotation.Output]>
>
<[string8][object][rigidbodygraphics]
  <[string8][Name][Step1Graphic]>
  <[uint32][PositionID][Ladder.R]>
  <[uint32][OrientationID][Ladder.Q]>
  <[string8][GeometryList][ Ladder-a ]>
>

<[string8][object][graphics_input]
  <[string8][Name][ServoLadderTranslation]>
  <[string8][InputID][ServoLadderTranslation.Output]>
  <[float64][Scaling][0.08]>
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<[string8][object][graphics_input]
  <[string8][Name][ServoLadderTranslation1]>
  <[string8][InputID][ServoLadderTranslation.Output]>
  <[float64][Scaling][0.16]>
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<[string8][object][graphics_input]
  <[string8][Name][ServoLadderTranslation2]>
  <[string8][InputID][ServoLadderTranslation.Output]>
  <[float64][Scaling][0.24]>
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  <[string8][Name][LadderTranslation]>
  <[tmvector3f][Axis][ 0.000000 0.034899 -0.999391 ]>
  <[float64][Input][ServoLadderTranslation.Output]>
>
<[string8][object][graphics_translation]
  <[string8][Name][LadderTranslation1]>
  <[tmvector3f][Axis][ 0.000000 0.034899 -0.999391 ]>
  <[float64][Input][ServoLadderTranslation1.Output]>
>
<[string8][object][graphics_translation]
  <[string8][Name][LadderTranslation2]>
  <[tmvector3f][Axis][ 0.000000 0.034899 -0.999391 ]>
  <[float64][Input][ServoLadderTranslation2.Output]>
>
<[string8][object][rigidbodygraphics]
  <[string8][Name][LadderBGraphic]>
  <[uint32][PositionID][Ladder.R]>
  <[uint32][OrientationID][Ladder.Q]>
  <[string8][GeometryList][ Ladder-b ]>
  <[string8][InputTransform][LadderTranslation.Output]>
>
```

```
<[string8][object][rigidbodygraphics]
  <[string8][Name][LadderCGraphic]>
  <[uint32][PositionID][Ladder.R]>
  <[uint32][OrientationID][Ladder.Q]>
  <[string8][GeometryList][ Ladder-c ]>
  <[string8][InputTransform][LadderTranslation1.Output]>
```

>

```
<[string8][object][rigidbodygraphics]
  <[string8][Name][Ladder0Graphic]>
  <[uint32][PositionID][Ladder.R]>
  <[uint32][OrientationID][Ladder.Q]>
  <[string8][GeometryList][ Ladder-0 ]>
  <[string8][InputTransform][LadderTranslation2.Output]>
```

>